Orientation Score Theory and its Solutions to Cortical PDE, ODE and Wavelet Models. R. Duits, (Eindhoven University of Technology)

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Lecture 1 (invertible multi-orientation image representations)

Introduction to Image Processing via Invertible Orientation Scores.

Content: In this 1st lecture we aim for introduction and motivation of the orientation score framework:

- What is an invertible orientation score?
- Why do we need invertible orientation scores?
- Why must we apply left-invariant processing on them?
- What medical image analysis applications can we tackle with them?

Exercise Topics:

- Condition numbers of the transformation.
- Proofs of general unitarity results.
- the Lie group structure on the domain of an orientation score.

Lecture 2 (design of multi-orientation image representations) Design of Invertible Orientation Scores of 2D and 3D images.

Content: In this 2^{nd} lecture we focus on the following topics:

- Design of 2D Cake-wavelets.
- Design of 3D Cake-wavelets.
- Relating the forward orientation score transform to inverse Fourier transform on SE(2).
- References to Tutorials of the Lie Analysis Mathematica 11 Package.

Exercise Topics:

- Design of cake-wavelets in Fourier domain (B-splines, Spherical Harmonics, Func-Transform)
- Analytic versions of cake-wavelets in both spatial and Fourier domains. (modified Zernike basis)
- Questions on playing with cake-wavelet design in our Lie Analysis package.

Lecture 3 (solutions to cortical models for contour completion and enhancement)

Exact Solutions to Linear Left-Invariant PDE's on SE(2) and on SE(3).

Content: In this 3rd lecture we focus on the following topics:

- Exact solutions to Mumford's direction Process on SE(2).
- Exact solutions to Hypo-elliptic Diffusion on SE(2).
- Exact solutions to Mumford's direction Process on SE(3).

Exercise Topics:

-A review on well-known (and related) exact solutions for diffusions and Tikhonov regularization on a sphere.

-Method of separation exercises tackling specific sub-problems on SE(d).

Lecture 4 (crossing-preserving diffusion via `straight curves' in orientation scores) *Crossing-preserving diffusions via locally adaptive frames in invertible orientation scores.* **Content:** In this 4th lecture we focus on the following topics:

- Exponential Curve fits of order 1.
- Exponential Curve fits of order 2.
- Crossing-Preserving Diffusions on SE(2).
- Crossing-Preserving Diffusions on SE(3).

Exercise Topics:

- Compute exponential curves in SE(2).

- Euler-Lagrange equations of exponential curve fits of order 1 on SE(2).
- Euler-Lagrange equations of exponential curve fits of order 2 on SE(2).

- The minus Cartan connection: "Straight curves" vs. "shortest curves".

Lecture 5 (tracking via `shortest curves' in orientation scores)

Globally Optimal Sub-Riemannian geodesics in the projective line bundle. Improvements via Asymmetric Finsler geometry: key-points instead of cusps ! Content: In this 5th lecture we illustrate geodesic tracking in orientation scores:

- Sub-Riemannian Geodesics in SE(2) and in the projective line bundle, and vessel-tracking applications.

- Sub-Riemannian Geodesics in SE(3) and DW-MRI applications.

- The problem of cusps in spatial projections of SR geodesics.

- The solution to the problem of cusps: Turn off the reverse gear of the Reeds-Shepp car.

Exercise Topics:

- Derive the Hamiltonian equations for sub-Riemannian geodesics in SE(2).

- Preservation laws and symmetries of sub-Riemannian geodesics in SE(d), d=2,3.

- Analyze the shape of the sub-Riemannian spheres on SE(2) and their intersection with the 1^{st} Maxwell set.

- Analyze the shape of the sub-Riemannian spheres on the projective line bundle and their intersection with the 1st Maxwell set.

- Apply a vessel-tracking in a challenging industrial medical imaging example in a prepared Mathematica 11 notebook.